

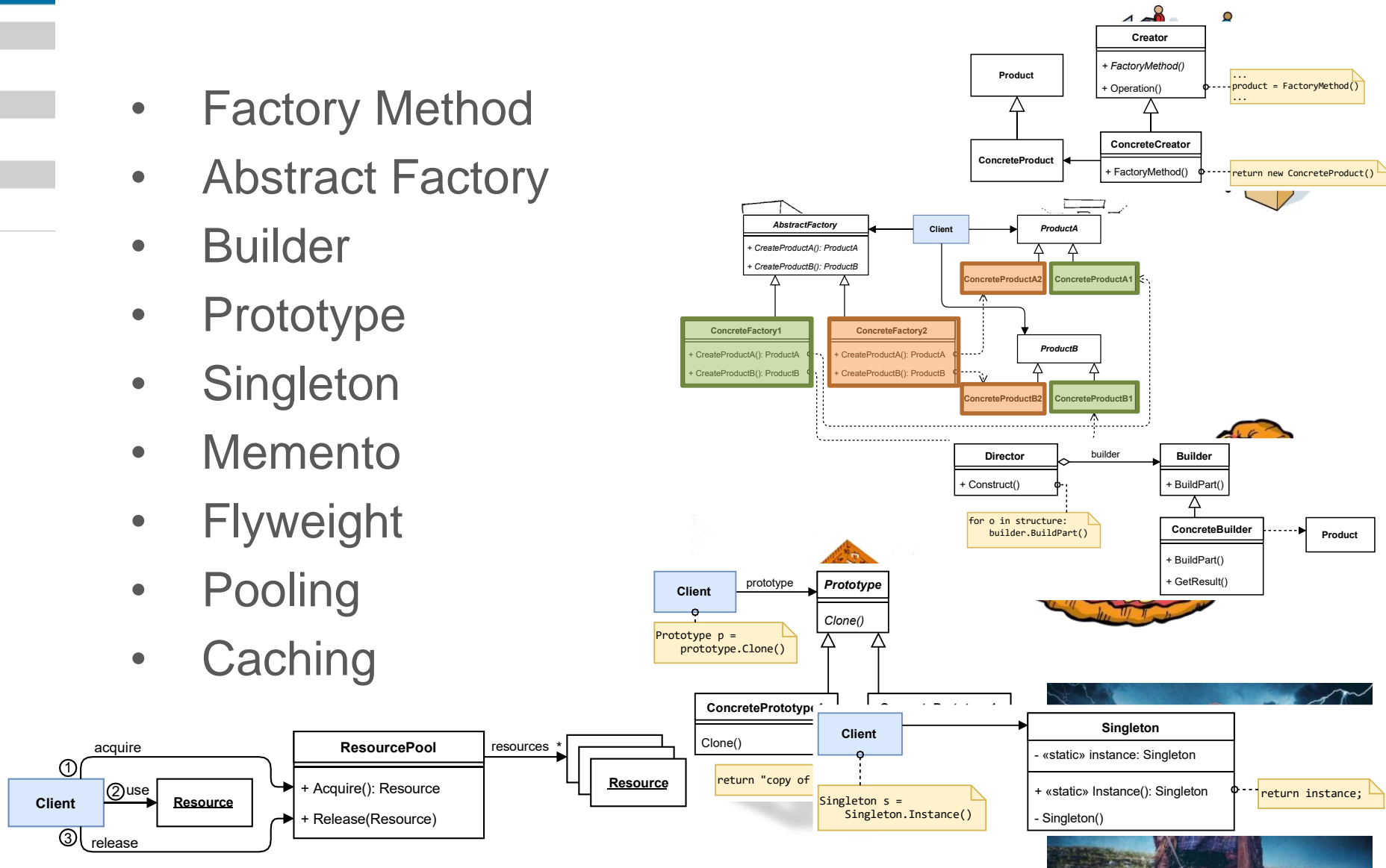
Design Patterns 448.058 (VO)

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Georg Macher

06.11.2019

Revision from last time...

- Factory Method
- Abstract Factory
- Builder
- Prototype
- Singleton
- Memento
- Flyweight
- Pooling
- Caching



Use-Case: VECTO



<http://reducingco2together.eu/>

https://ec.europa.eu/clima/policies/transport/vehicles/vecro_de

VECTO

Vehicle Energy Consumption Calculation Tool

There simply is no
'one-size-fits-all' approach
for heavy-duty vehicles



Figure from ACEA, 2016, [reducingco2together.eu](https://www.reducingco2together.eu/),
<https://www.reducingco2together.eu/assets/trucks/trucks-two-inforgraphic.png>



- The shape of the vehicles, which depends on their daily 'mission'.
- The same tractor or engine may end up pulling very different trailers and combinations, affecting the CO2 emissions of the complete vehicle.
- The usage pattern of the vehicles and their cargo, in other words, 'the work they do'.



Is the payload heavy or light,
large or small?



Is the road flat or hilly?



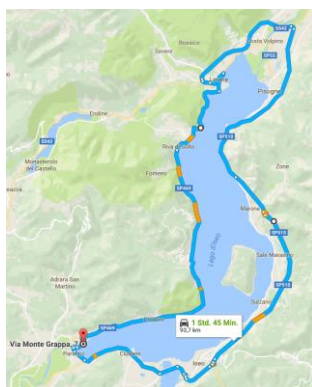
Will the vehicle travel over a long distance
in one go, or is the journey short
with many starts and stops?

All these variables result in different CO2 emissions.

Figure from ACEA, 2016, [reducingco2together.eu](https://www.reducingco2together.eu),
<https://www.reducingco2together.eu/assets/trucks/trucks-two-inforgraphic.png>

VECTO

Vehicle Energy Consumption Calculation Tool



VECTO 3.2.0.940 - Declaration Mode

Job Files (1/1) Options

VECTO Job File

☐ Engine Only Mode

General Driver Model

Vehicle: Class5_Tractor.vveh

Engine: Engine_325kW_12.7i.veng

Gearbox: AMT_12.vgbox

Auxiliaries

Auxiliary Type: Classic Vecto Auxiliary

Advanced Aux File

Constant Aux Load [W]

ID	Type	Technology
FAN	Fan	Belt driven or driven via trans. - Electronically controlled visco clutch
STP	Steering pump	Fixed displacement with elec. control
AC	HVAC	Default
ES	Electric System	Standard technology
PS	Pneumatic System	Medium Supply 2-stage + ESS + AMS

Cycles

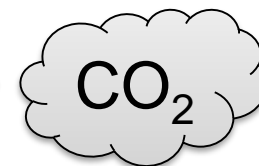
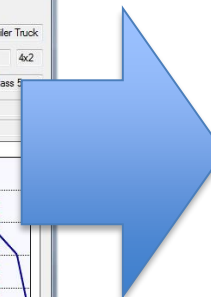
LongHaul
LongHaulEMS
RegionalDelivery
RegionalDeliveryEMS

12.7i 325 kW 325kW 12.7i Engine

12-Speed AMT tractor_12gear_example

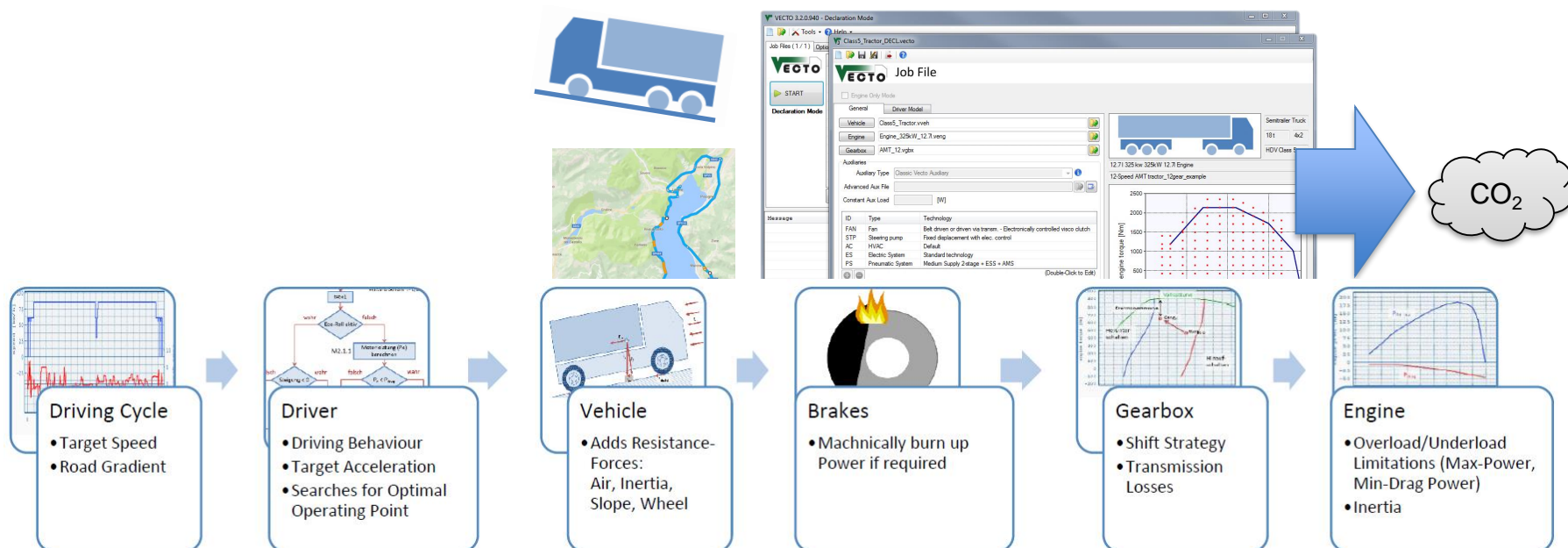
Max. Torque: 2134 Nm; Max. Power: 325.0 kW; n_{rated}: 1736 rpm; n_{95h}: 1857 rpm

Save Cancel



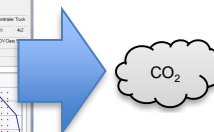
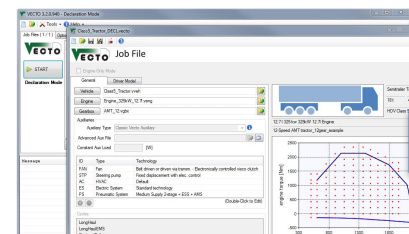
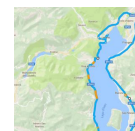
VECTO

Vehicle Energy Consumption Calculation Tool



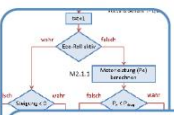
VECTO

Vehicle Energy Consumption Calculation Tool



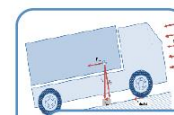
Driving Cycle

- Target Speed
- Road Gradient



Driver

- Driving Behaviour
- Target Acceleration
- Searches for Optimal Gear



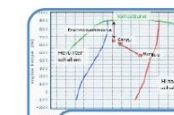
Vehicle

- Adds Resistance Forces: Air, Inertia, Rolling



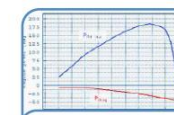
Brakes

- Mechanically burn up Power if required



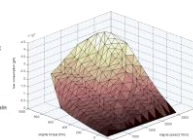
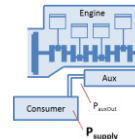
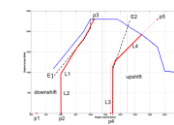
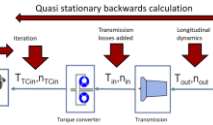
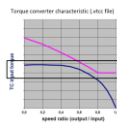
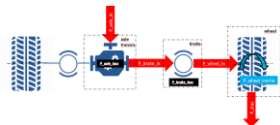
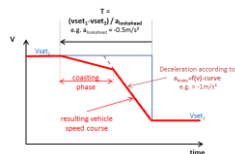
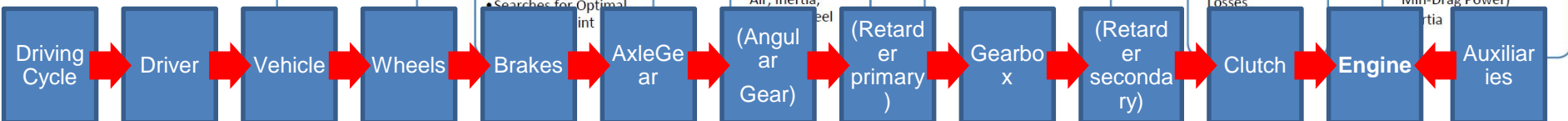
Gearbox

- Shift Strategy
- Transmission Losses



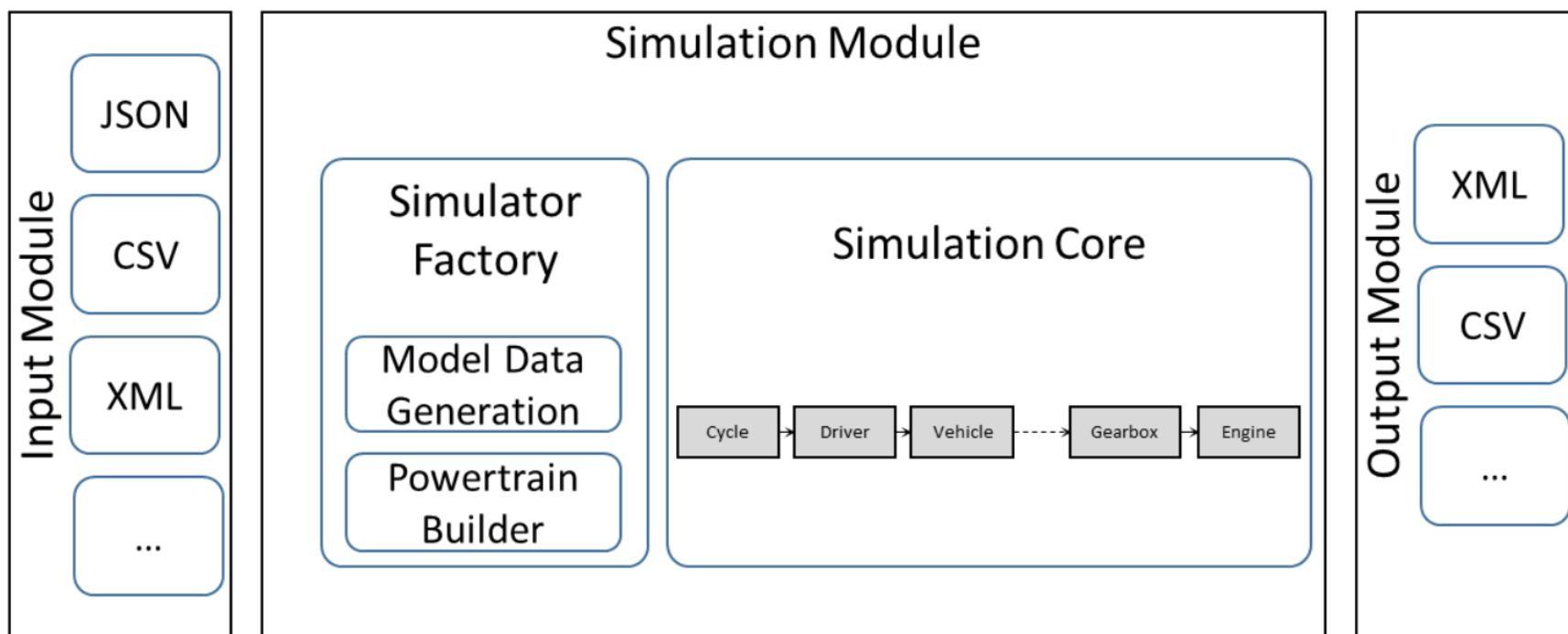
Engine

- Overload/Underload Limitations (Max-Power, Min-Drive Power)





Graphical User Interface / Commandline Interface





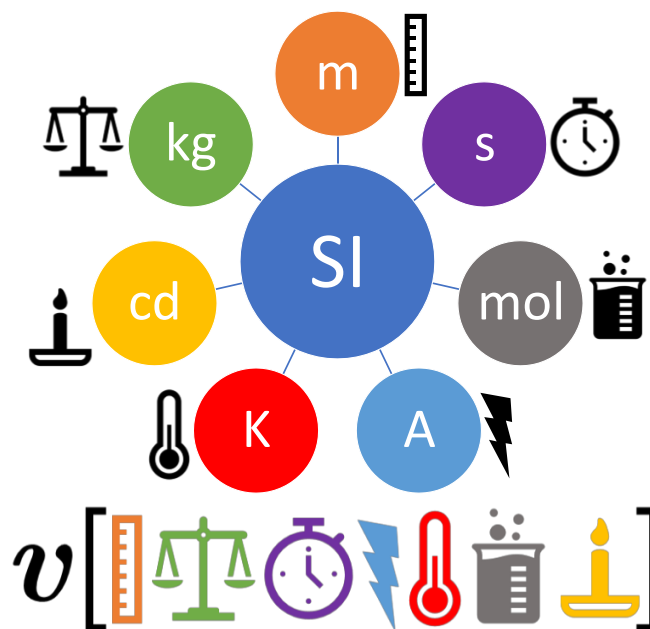
- Development Time: ~7 Years (+ previous works)
- Developed in C# and VB.net
- Lines of Code: ~50 000
- Classes: 900
- Methods: 10 000 (w/o getter/setter: ~4 500)
- Σ Cyclomatic Complexity: ~18 000
- Avg. Complexity / Method: ~2-3
- LOC Test Coverage: ~85%

VECTO Live Demonstration...



“VECTO presents itself”, Daimler AG, 10.10.2018: <https://www.youtube.com/watch?v=sf30XrjEJ2M>

SI Units



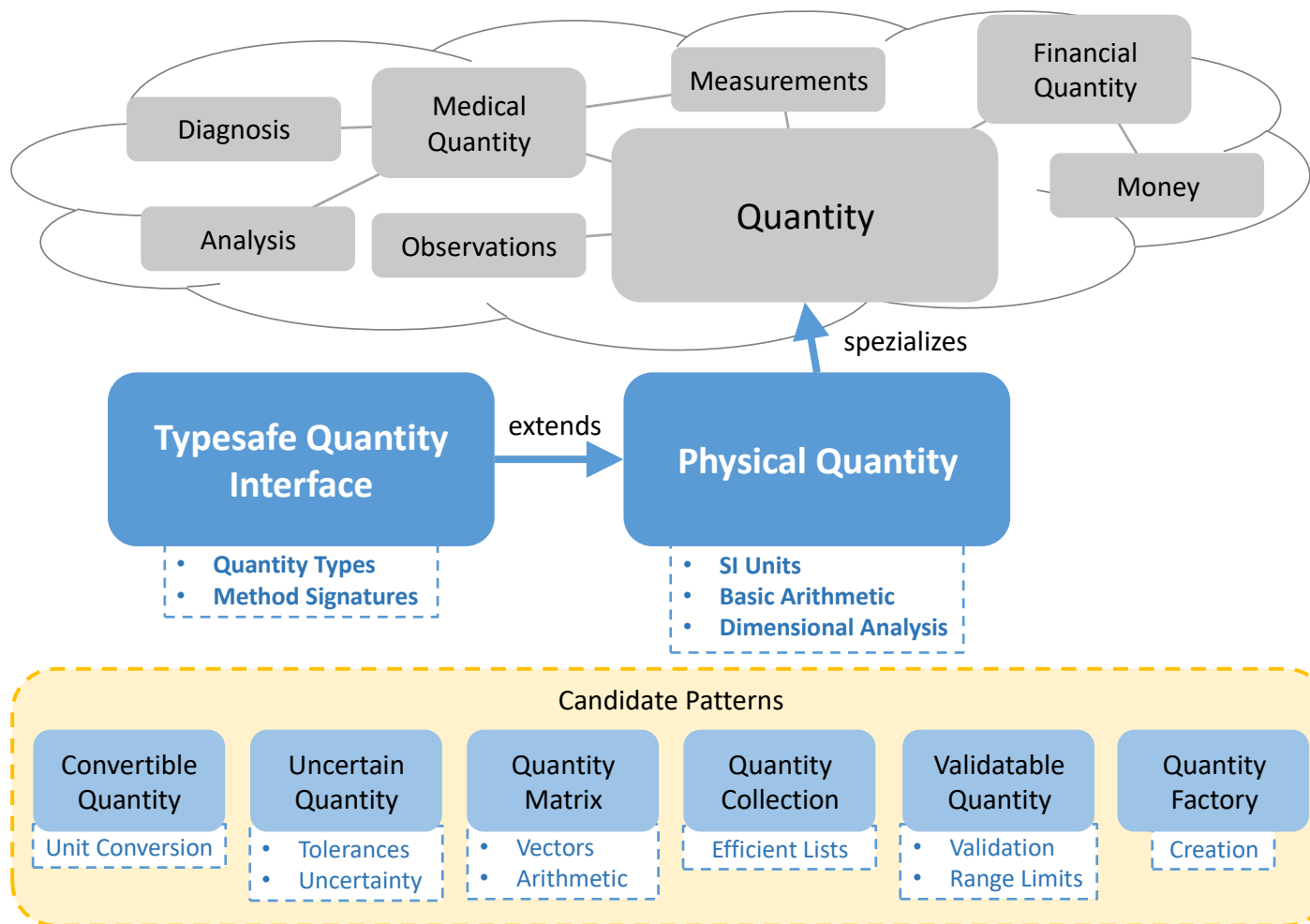
SI Unit $:= v [Q]$

v := a scalar value (v) or a vector (\vec{v})

$$[Q] := [\alpha, \beta, \gamma, \delta, \epsilon, \zeta, \eta] \hat{=} [[m]^\alpha \times [kg]^\beta \times [s]^\gamma \times [A]^\delta \times [K]^\epsilon \times [mol]^\zeta \times [cd]^\eta]$$

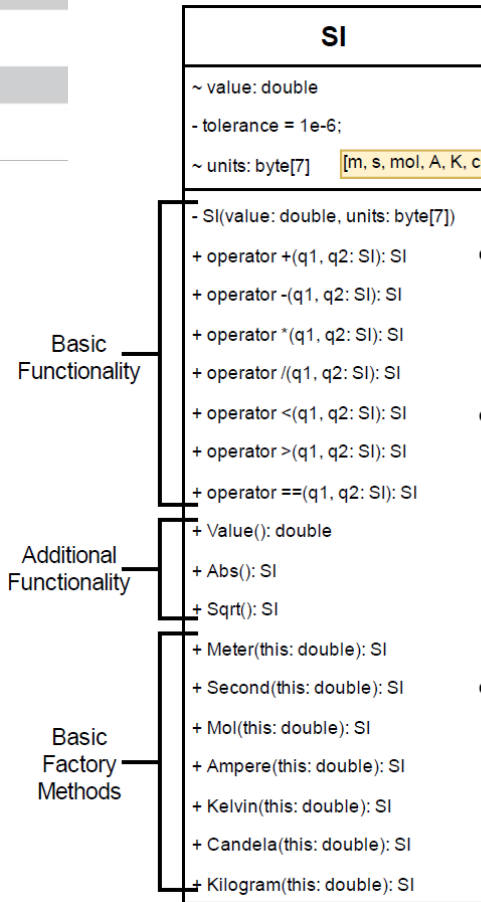
$$\begin{aligned} \mathbf{v} [Q] &= \mathbf{v} \begin{bmatrix} [m], [kg], [s], [A], [K], [mol], [cd] \end{bmatrix} \\ 5 \text{ kg} &= 5 \begin{bmatrix} 0, 1, 0, 0, 0, 0, 0 \end{bmatrix} \\ 2.8 \text{ m/s}^2 &= 2.8 \begin{bmatrix} 1, 0, -2, 0, 0, 0, 0 \end{bmatrix} \\ 7 \text{ Nm} = 7 \text{ kgm}^2/\text{s}^2 &= 7 \begin{bmatrix} 2, 1, -2, 0, 0, 0, 0 \end{bmatrix} \end{aligned}$$

Physical Quantities Pattern Language



Physical Quantity

Ensure correctness of physical units for calculations.



```
public static operator +(SI q1, SI q2) {
    if (q1.units == q2.units)
        return new SI(q1.value+q2.value, q1.units);
    throw Exception("Addition for different units is not allowed");
}
```

```
public static operator <(SI q1, SI q2) {
    if (q1.units == q2.units)
        return q1.value < q2.value + this.tolerance;
    throw Exception("Comparison for different units is not allowed");
}
```

```
public SI Second(this double self){
    return new SI(self, [0, 1, 0, 0, 0, 0, 0])
}
```

$$+ : v_1 [Q] + v_2 [Q] := v_1 + v_2 [Q]$$

$$- : v_1 [Q] - v_2 [Q] := v_1 - v_2 [Q]$$

$$* : v_1 [Q_1] * v_2 [Q_2] := v_1 * v_2 [Q_1 + Q_2]$$

$$/ : \frac{v_1 [Q_1]}{v_2 [Q_2]} := \frac{v_1}{v_2} [Q_1 - Q_2]$$

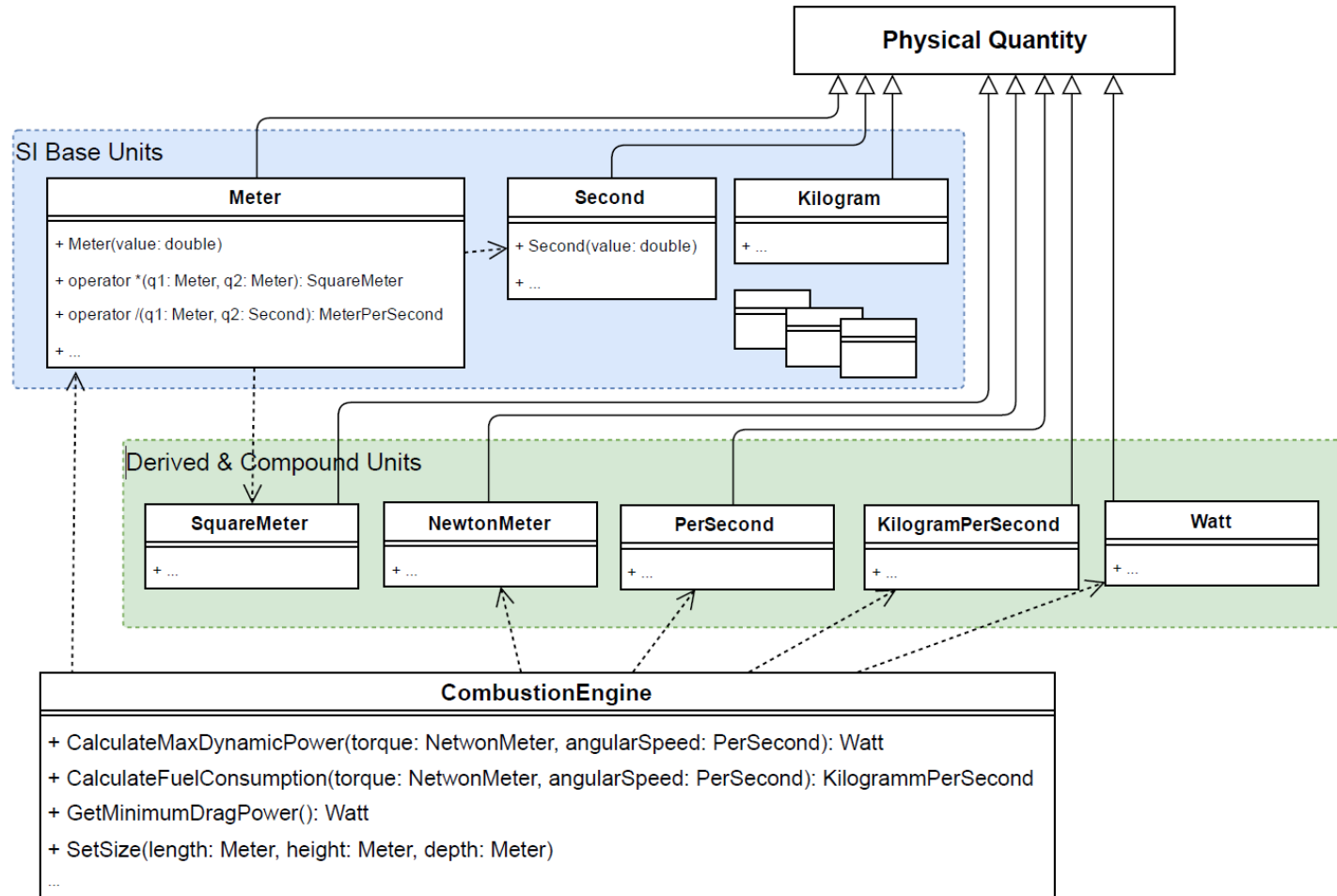
$$< : v_1 [Q] < v_2 [Q] \Leftrightarrow v_1 < v_2 + \varepsilon$$

$$> : v_1 [Q] > v_2 [Q] \Leftrightarrow v_1 + \varepsilon > v_2$$

$$= : v_1 [Q] = v_2 [Q] \Leftrightarrow v_1 - \varepsilon < v_2 < v_1 + \varepsilon$$

Typesafe Quantity Interfaces

Make physical units explicit and verifiable at compile time.



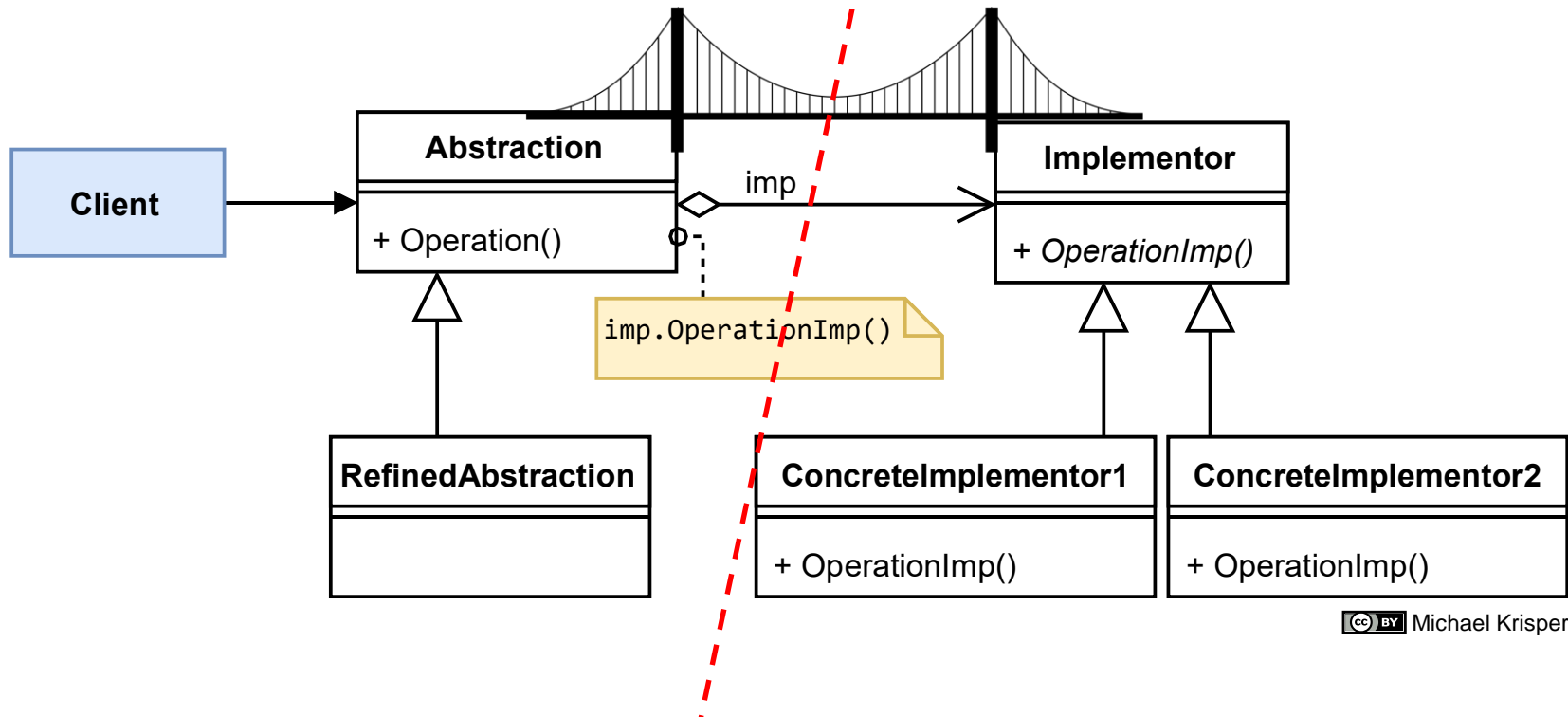
Learning Goals for Today

Communication Patterns:

- **BRIDGE**
- **BROKER**
- **MEDIATOR**
- **BLACKBOARD**
- **MICROKERNEL**
- **CLIENT-DISPATCHER-SERVER / LOOKUP**
- **MESSAGES**
- **MESSAGE ENDPOINT**
- **MESSAGE TRANSLATOR**
- **MESSAGE ROUTER**
- **REQUEST HANDLER**
- **REQUESTOR**

Bridge

Decouple abstractions from implementations



Bridge

Context: Application with Abstraction and Implementation Hierarchies

Problem: How to decouple the development of abstractions from its implementations

Forces:

- Avoid permanent binding between abstraction and implementation
- Both sides should be extensible by subclassing
- Changes should be contained to one side
- You want to hide the implementation side completely
- Implementations should be compatible to multiple abstractions

Solution:

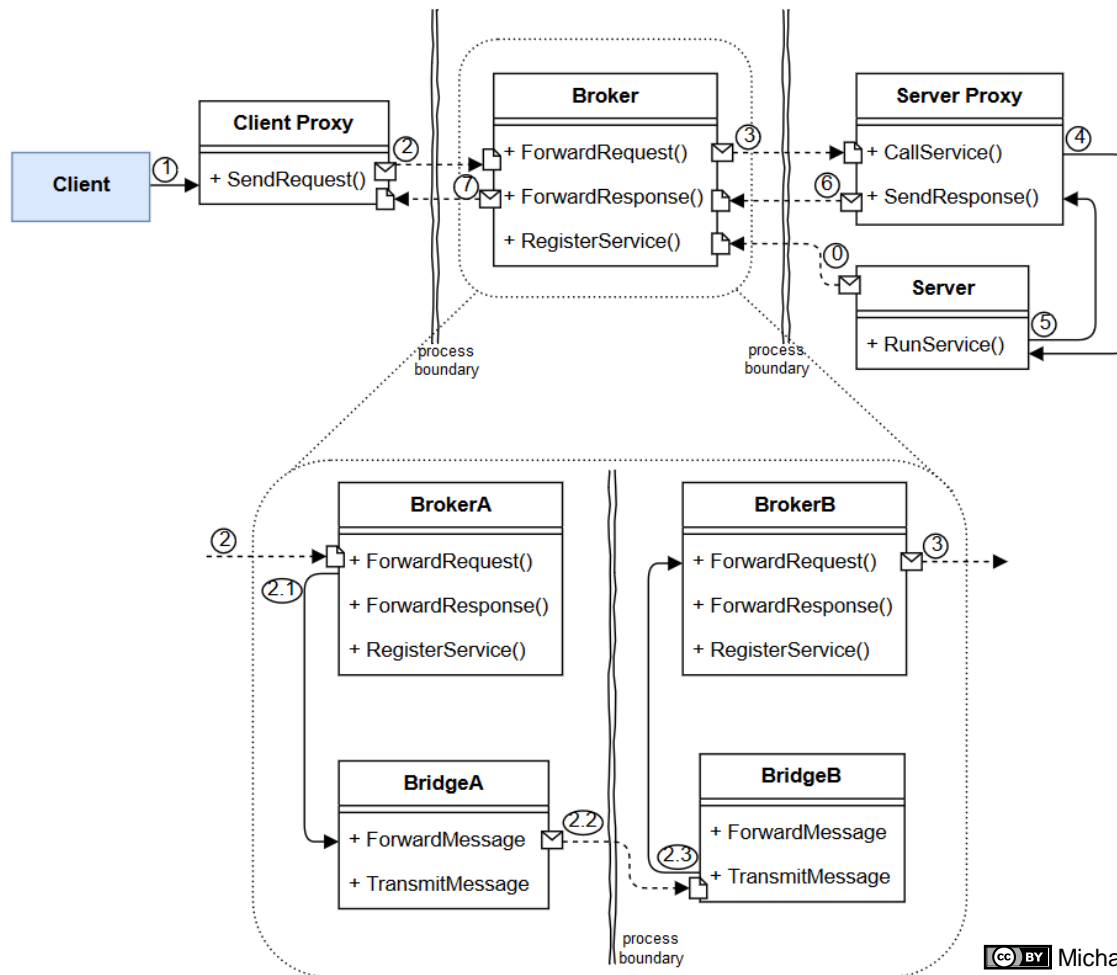
- Create two interfaces:
 1. Implementor-Interface (internal primitives)
 2. Abstraction-Interface (client-requirements)
- Implement those Interfaces with individual classes.
- Only use the implementation-interface in the abstraction

Consequences:

- + Decoupling of abstraction and implementation
- + Improved extensibility: Both sides can grow independently
- + Hiding implementation details from client
- + Implementation can be configured at runtime
- + Elimination of compile-time dependencies
- + Encourages layering
- ~ Who defines the composition? (Who builds the bridge?)
- Higher complexity (more classes, more interfaces)

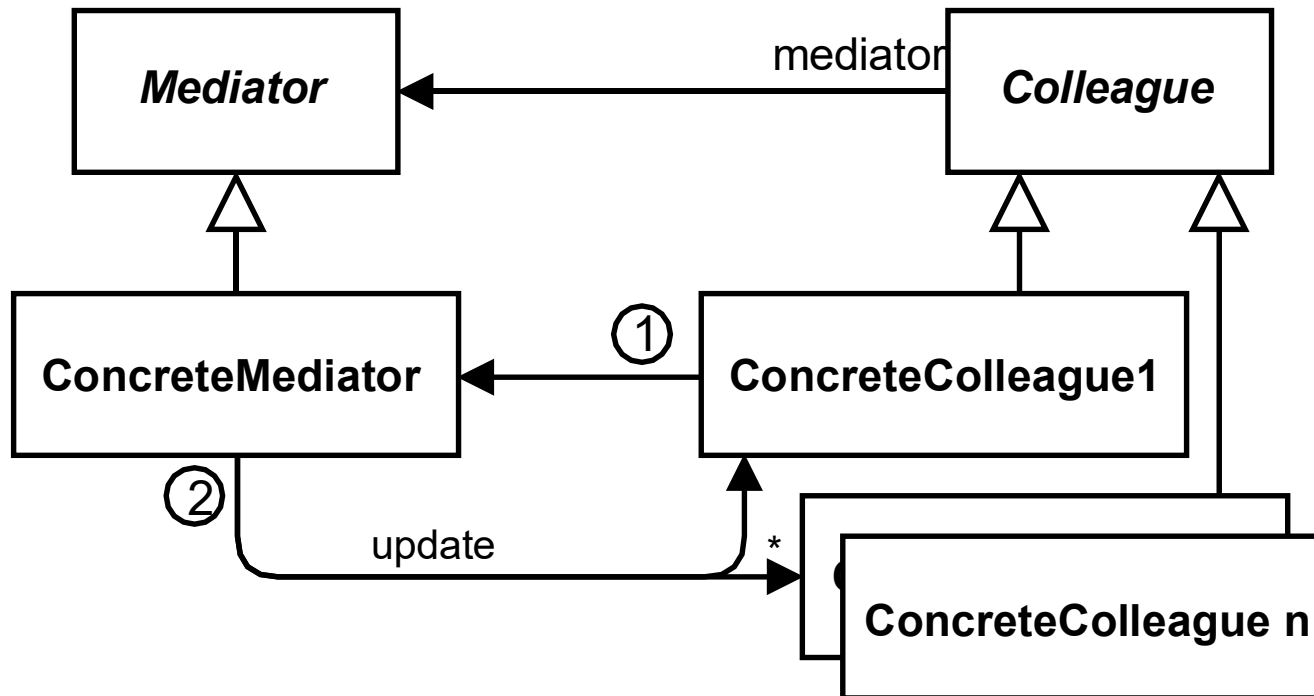
Broker

Manage dynamic communication between clients and servers in distributed systems.



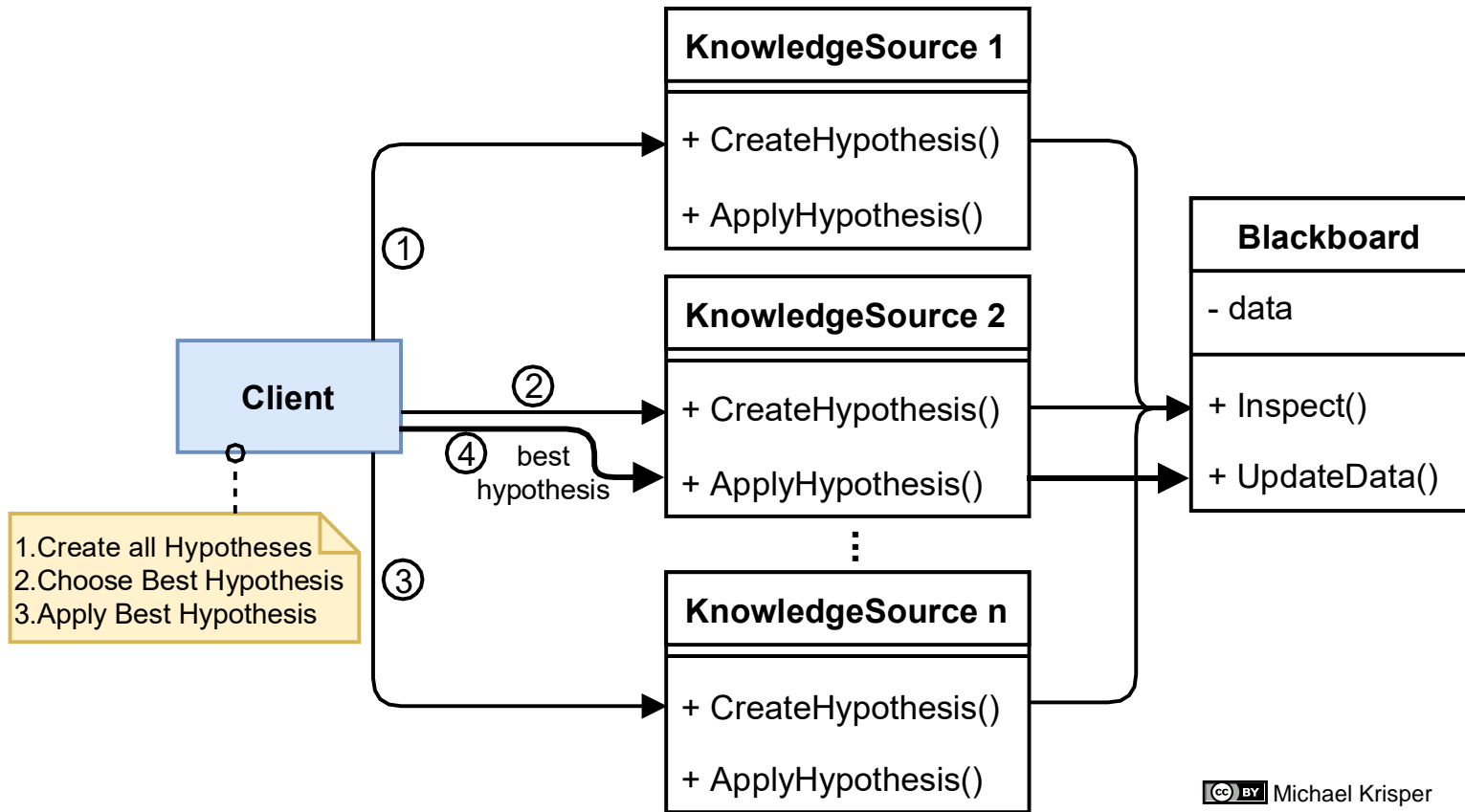
Mediator

Mediate communication between multiple objects



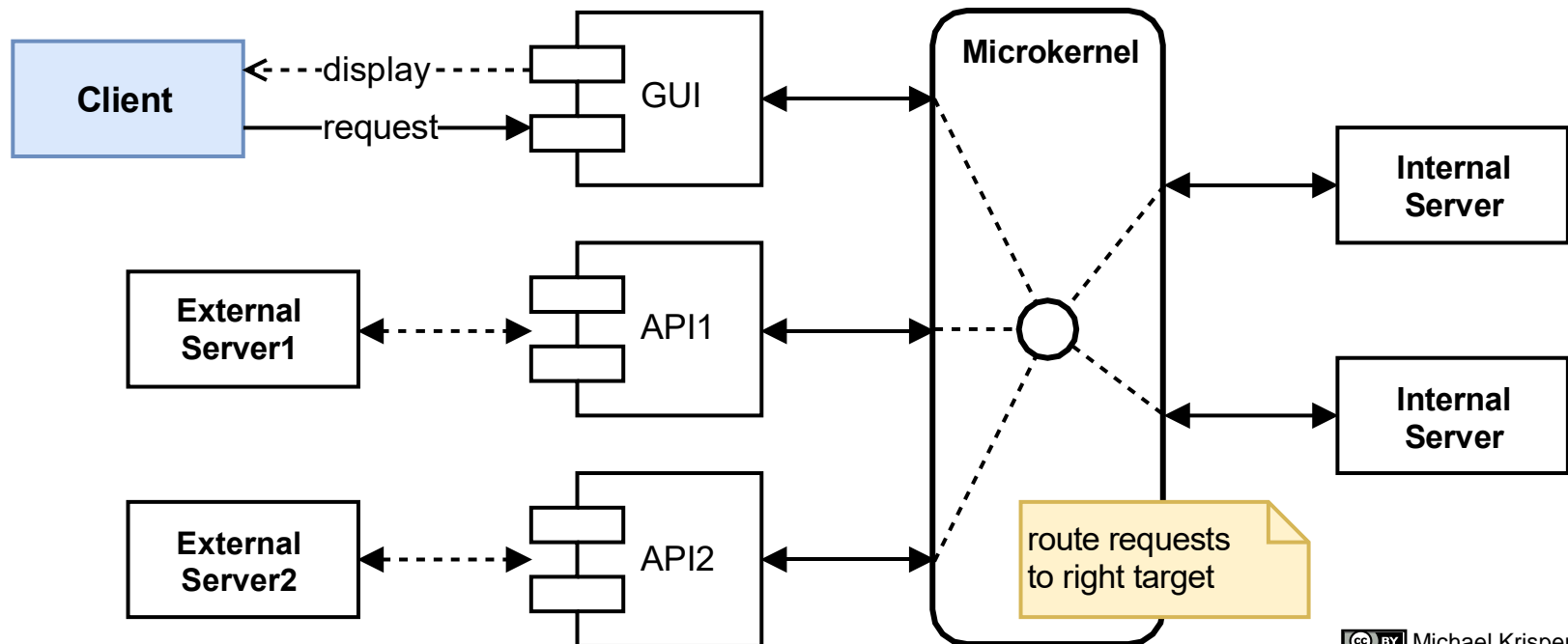
Blackboard

Collaborate on common data to get the best solution.



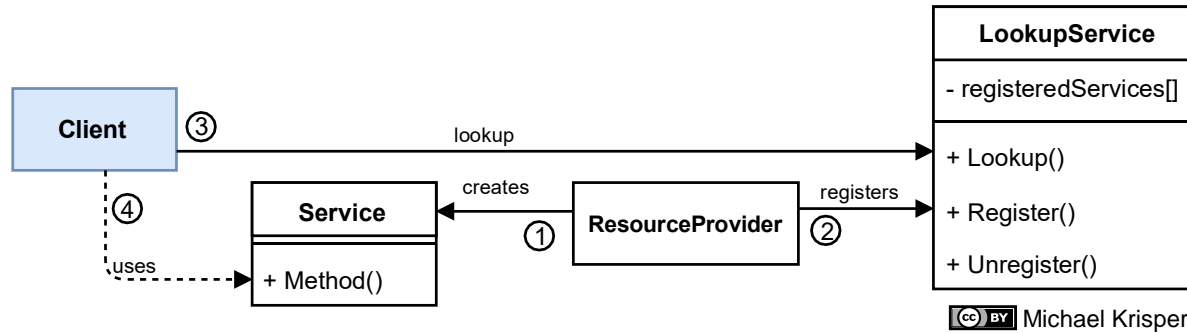
Microkernel

Route requests to the responsible components



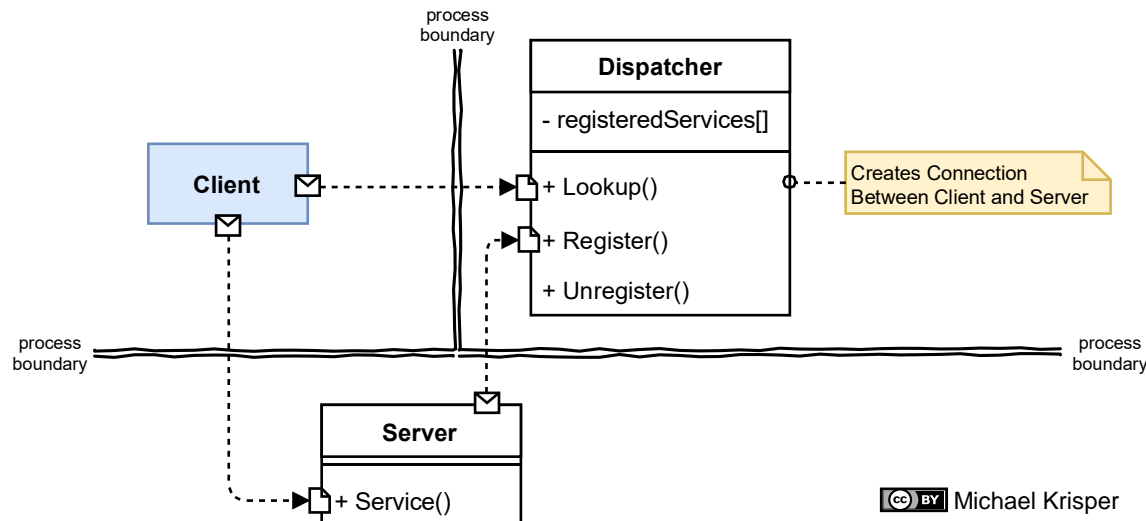
Lookup

Store service-providers and let clients search for it.



Client-Dispatcher-Server

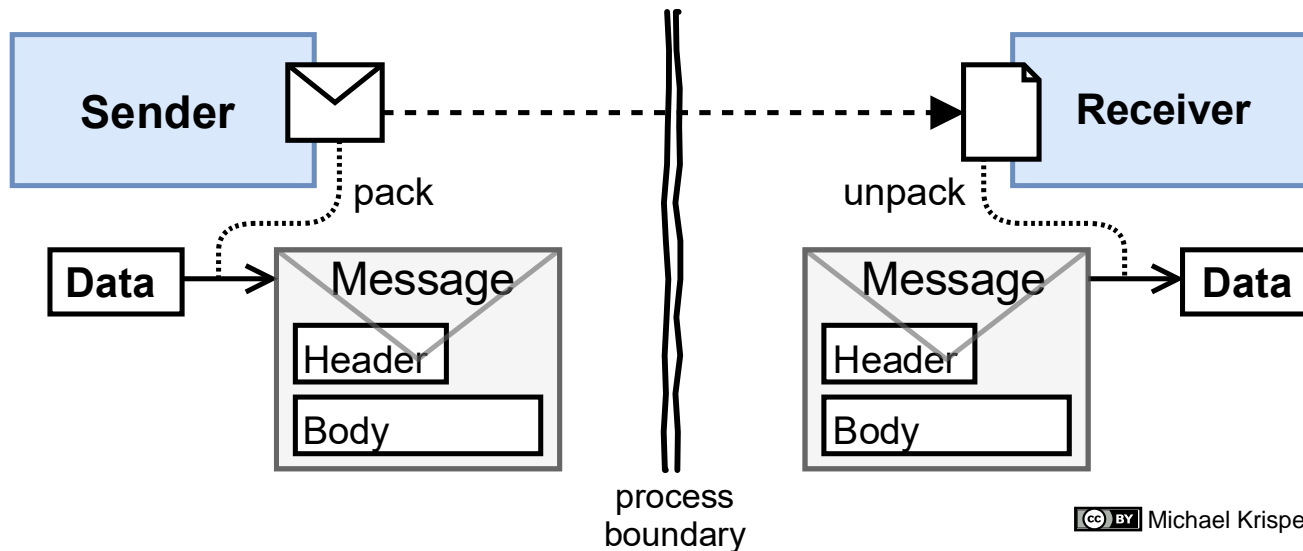
Store distributed service-providers and connect clients to them.



Messaging

Messages

Encapsulate information in a standardized way



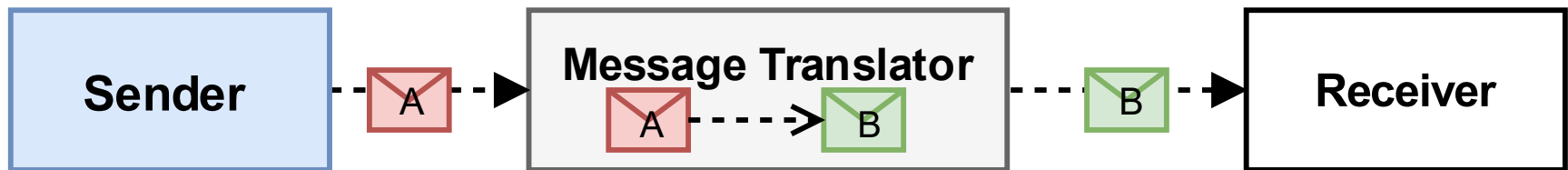
Message Endpoint

Provide functionality to send and receive messages



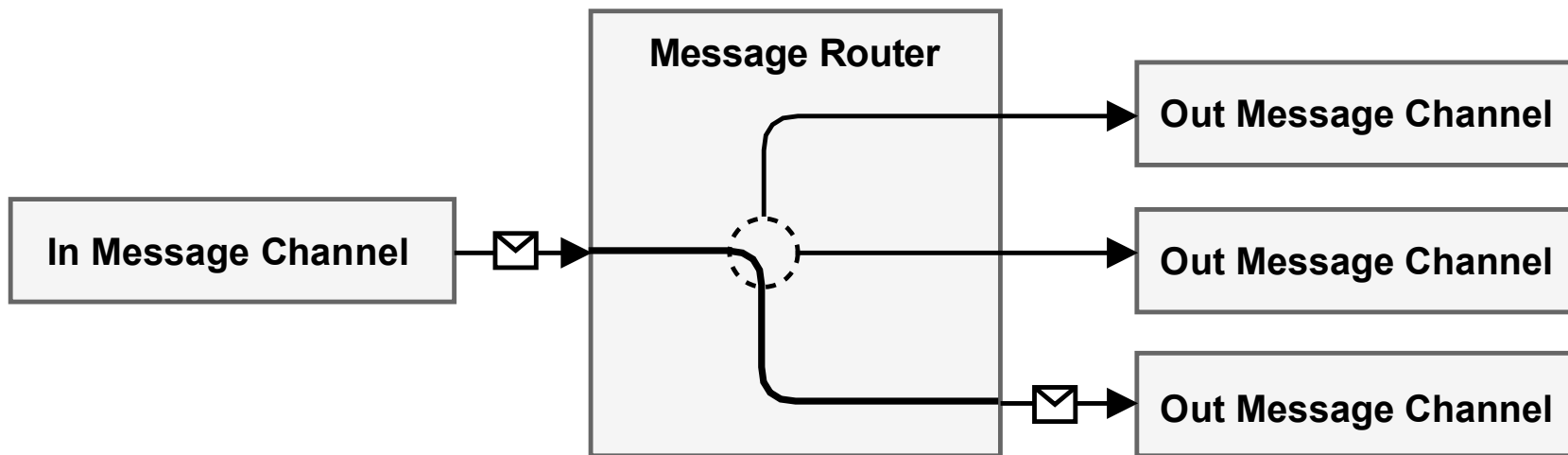
Message Translator *(Converter, Transformer)*

Translate between different message formats

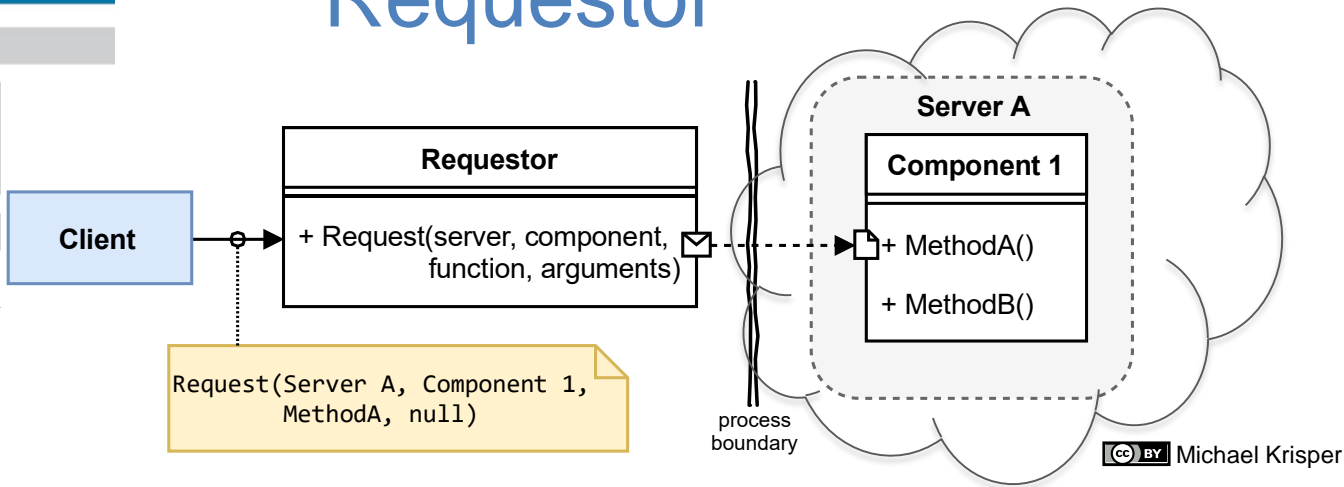


Message Router

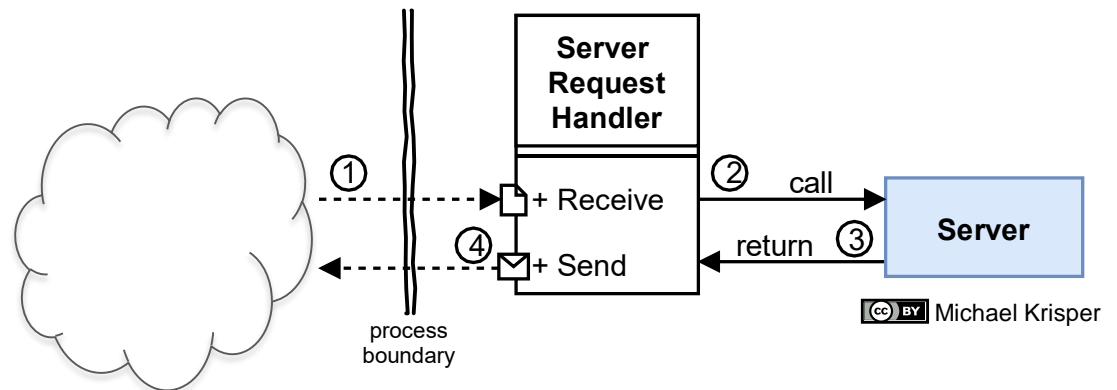
Route messages to the right receiver



Requestor



Request Handler



Summary

Communication Patterns:

- MEDIATOR
- BLACKBOARD
- MICROKERNEL
- BRIDGE
- BROKER
- MESSAGES
- MESSAGE ENDPOINT
- MESSAGE TRANSLATOR
- MESSAGE ROUTER
- REQUEST HANDLER
- REQUESTOR